

Laplace Transform

Pierre-Simon Laplace (1749-1827)

Nikesh Bajaj
 nikesh.14730@lpu.co.in
 Digital Signal Processing
 School of Electronics and Communication
 Lovely Professional University

Introduction

- Why
- How

2 By: Nikesh Bajaj

Moving from Fourier to Laplace

- $F(j\omega) =$ Fourier
- $F(s)$ Laplace
- $F(s) = \mathcal{L}\{f(t)\} \doteq \int_0^{\infty} e^{-st} f(t) dt$ Unilateral Laplace

3 By: Nikesh Bajaj

Example

- $x(t) = \exp(-at)u(t)$
- $x(t) = -\exp(-at)u(-t)$
- $x(t) = 3\exp(-2t)u(t) - 2\exp(-at)u(t)$
- $x(t) = s(t)$

4 By: Nikesh Bajaj

Example

$f(t) = 1, 0 \leq t < \infty.$

5 By: Nikesh Bajaj

Pairs

$f(t) = 1, t \geq 0$	$F(s) = \frac{1}{s}, s > 0$
$f(t) = t^n, t \geq 0$	$F(s) = \frac{n!}{s^{n+1}}, s > 0$
$f(t) = e^{at}, t \geq 0$	$F(s) = \frac{1}{s-a}, s > a$
$f(t) = \sin(kt), t \geq 0$	$F(s) = \frac{k}{s^2+k^2}$
$f(t) = \cos(kt), t \geq 0$	$F(s) = \frac{s}{s^2+k^2}$
$f(t) = \sinh(kt), t \geq 0$	$F(s) = \frac{k}{s^2-k^2}, s > k $
$f(t) = \cosh(kt), t \geq 0$	$F(s) = \frac{s}{s^2-k^2}, s > k $

6 By: Nikesh Bajaj

Example

7 By: Nikesh Bajaj

Properties of ROC

PROPERTIES OF THE REGION OF CONVERGENCE

- The ROC contains no poles

$$X(s) = \frac{N(s)}{D(s)}$$

poles of $X(s) \Rightarrow D(s) = 0$

- The ROC of $X(s)$ consists of a strip parallel to the $j\omega$ -axis in the s -plane
- $\mathcal{F}\{x(t)\}$ converges \Leftrightarrow ROC includes the $j\omega$ -axis in the s -plane

8 By: Nikesh Bajaj

Property 1: ROC does not contain any pole

1. No Poles in ROC

$$X(s) = \frac{1}{(s+1)(s+2)}$$

9 By: Nikesh Bajaj

Property 2: for finite duration and absolutely integral signal ROC is entire s-plane

2. Finite duration signal

- $x(t)$ finite duration \Rightarrow ROC is entire s -plane

10 By: Nikesh Bajaj

- $x(t)$ finite duration \Rightarrow ROC is entire s -plane

11 By: Nikesh Bajaj

Property 3: for right sided signal if $X(s)$ convergence at p_1 and will also converge at $p_2 > p_1$

3. Right sided signal

$x(t)$ right-sided and $\text{Re}\{s\} = \sigma_0$ is in ROC \Rightarrow all values for which $\text{Re}\{s\} > \sigma_0$ are in ROC

$x(t)$ right-sided and $X(s)$ rational \Rightarrow ROC is to the right of the rightmost pole.

12 By: Nikesh Bajaj

Property 4: for left sided signal if $X(s)$ convergence at $p1$ and will also converge at $p2 < p1$

4. Left sided signal

- $x(t)$ left-sided and $Re\{s\} = \sigma_0$ is in ROC
 => all values for which $Re\{s\} < \sigma_0$ are in ROC
- $x(t)$ left-sided and $X(s)$ rational
 => ROC to the left of the leftmost pole.

13

By: Nikesh Bajaj

Property 5: for two sided signal ROC will be strip

5. Two sided signal

- $x(t)$ two-sided and $Re\{s\} = \sigma_0$ is in ROC
 => ROC is a strip in the s-plane

14

By: Nikesh Bajaj

Properties

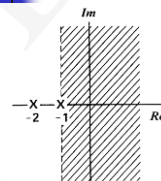
Property 6: ROC is bounded by poles or can extends to infinity.

Property 7: ROC is a strips, parallel to jw axis

15

By: Nikesh Bajaj

Example



$$X(s) = \frac{1}{(s+1)(s+2)} \quad Re\{s\} > -1$$

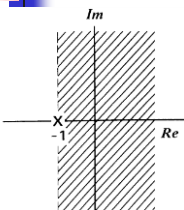
$$= \frac{1}{s+1} - \frac{1}{s+2} \quad Re\{s\} > -1$$

16

By: Nikesh Bajaj

$$X_1(s) = \frac{1}{s+1} \quad Re\{s\} > -1$$

$$x_1(t) = e^{-t} u(t)$$

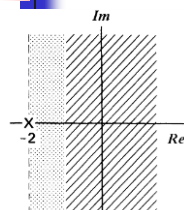


17

By: Nikesh Bajaj

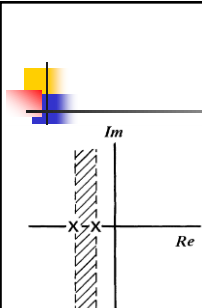
$$X_2(s) = \frac{-1}{s+2} \quad Re\{s\} > -1$$

$$x_2(t) = -e^{-2t} u(t)$$



18

By: Nikesh Bajaj



$$X(s) = \frac{1}{(s+1)(s+2)} \quad -2 < \text{Re}\{s\} < -1$$

$$= \frac{1}{s+1} - \frac{1}{s+2} \quad -2 < \text{Re}\{s\} < -1$$

19 By: Nikesh Bajaj

Properties of Laplace

Table 7: Properties of the Laplace Transform

Property	Signal	Transform	ROC
	$x(t)$	$X(s)$	R
	$x_1(t)$	$X_1(s)$	R_1
	$x_2(t)$	$X_2(s)$	R_2
Linearity	$ax_1(t) + bx_2(t)$	$aX_1(s) + bX_2(s)$	At least $R_1 \cap R_2$
Time shifting	$x(t - t_0)$	$e^{-st_0}X(s)$	R
Shifting in the s -Domain	$e^{st_0}x(t)$	$X(s - s_0)$	Shifted version of R [i.e., s is in the ROC if $(s - s_0)$ is in R]

20 By: Nikesh Bajaj

Properties

Table 7: Properties of the Laplace Transform

Property	Signal	Transform	ROC
	$x(t)$	$X(s)$	R
	$x_1(t)$	$X_1(s)$	R_1
	$x_2(t)$	$X_2(s)$	R_2
Time scaling	$x(at)$	$\frac{1}{ a }X\left(\frac{s}{a}\right)$	"Scaled" ROC (i.e., s is in the ROC if (s/a) is in R)
Conjugation	$x^*(t)$	$X^*(s^*)$	R
Convolution	$x_1(t) * x_2(t)$	$X_1(s)X_2(s)$	At least $R_1 \cap R_2$
Differentiation in the Time Domain	$\frac{d}{dt}x(t)$	$sX(s)$	At least R
Differentiation in the s -Domain	$-tx(t)$	$\frac{d}{ds}X(s)$	R
Integration in the Time Domain	$\int_{-\infty}^t x(\tau)d(\tau)$	$\frac{1}{s}X(s)$	At least $R \cap \{\text{Re}\{s\} > 0\}$

22 By: Nikesh Bajaj

Problem

- $x(t) = \exp(-t) \frac{d}{dt} (\exp(-(t+1))u(t+1))$
- $x(t) = \int_{-\infty}^t \exp(2T) \sin(T) u(T) dT$ -inf to t

22 By: Nikesh Bajaj

Initial and Final value theorem

Initial- and Final Value Theorems

If $x(t) = 0$ for $t < 0$ and $x(t)$ contains no impulses or higher-order singularities at $t = 0$, then

$$x(0^+) = \lim_{s \rightarrow \infty} sX(s)$$

If $x(t) = 0$ for $t < 0$ and $x(t)$ has a finite limit as $t \rightarrow \infty$, then

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$$

23 By: Nikesh Bajaj

Inverse Laplace

- Partial Fraction method

24 By: Nikesh Bajaj